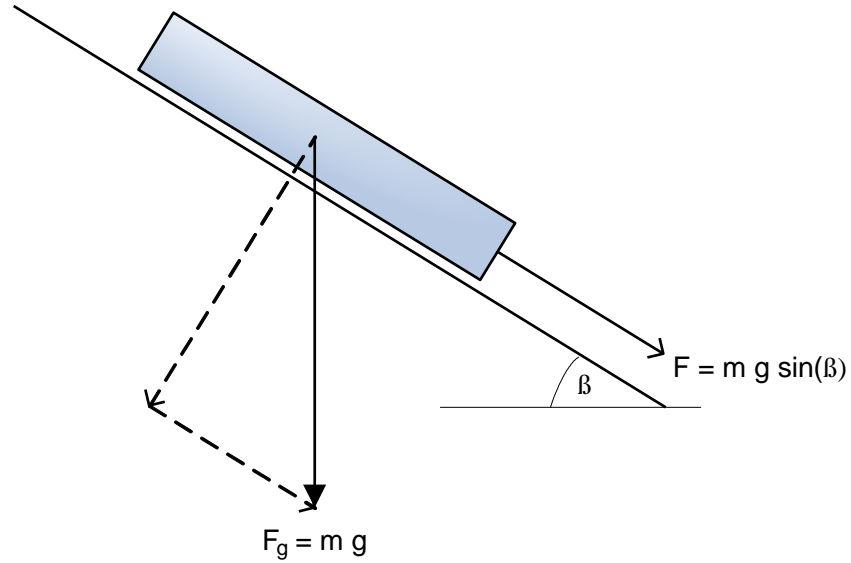




CR874/CR1435 Gradients. CR

Maarten Bartholomeus

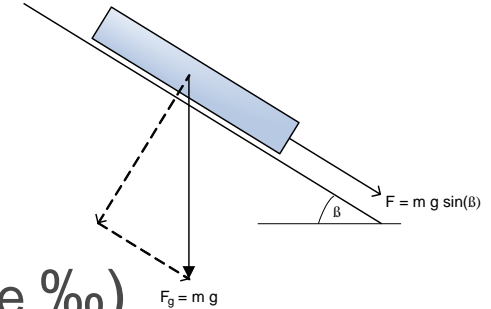
ProRail



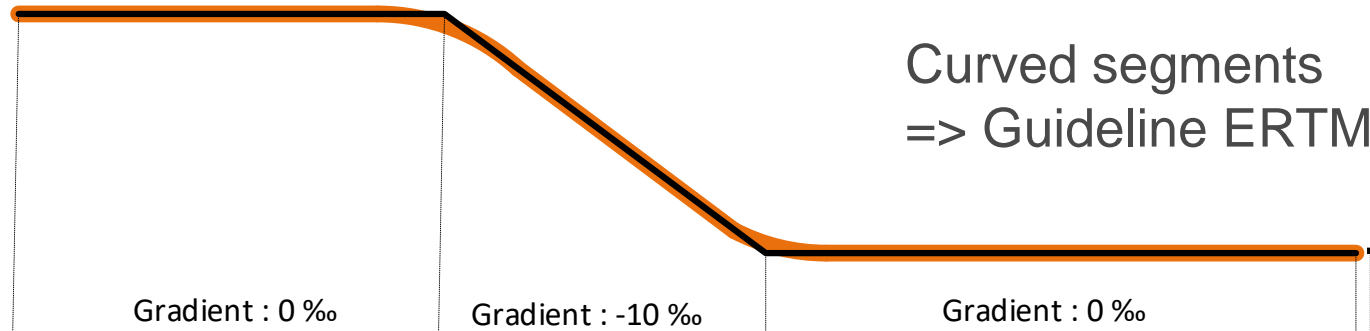
CR1435 Gradient under the train

ERTMS takes slopes (gradient) into account

- A slope has impact on the deceleration
 - $A_{\text{safe}}(V,d) = A_{\text{brake_safe}}(V,d) + A_{\text{gradient}}(d)$
 - For Cargo train can A_{safe} be reduced to 50%

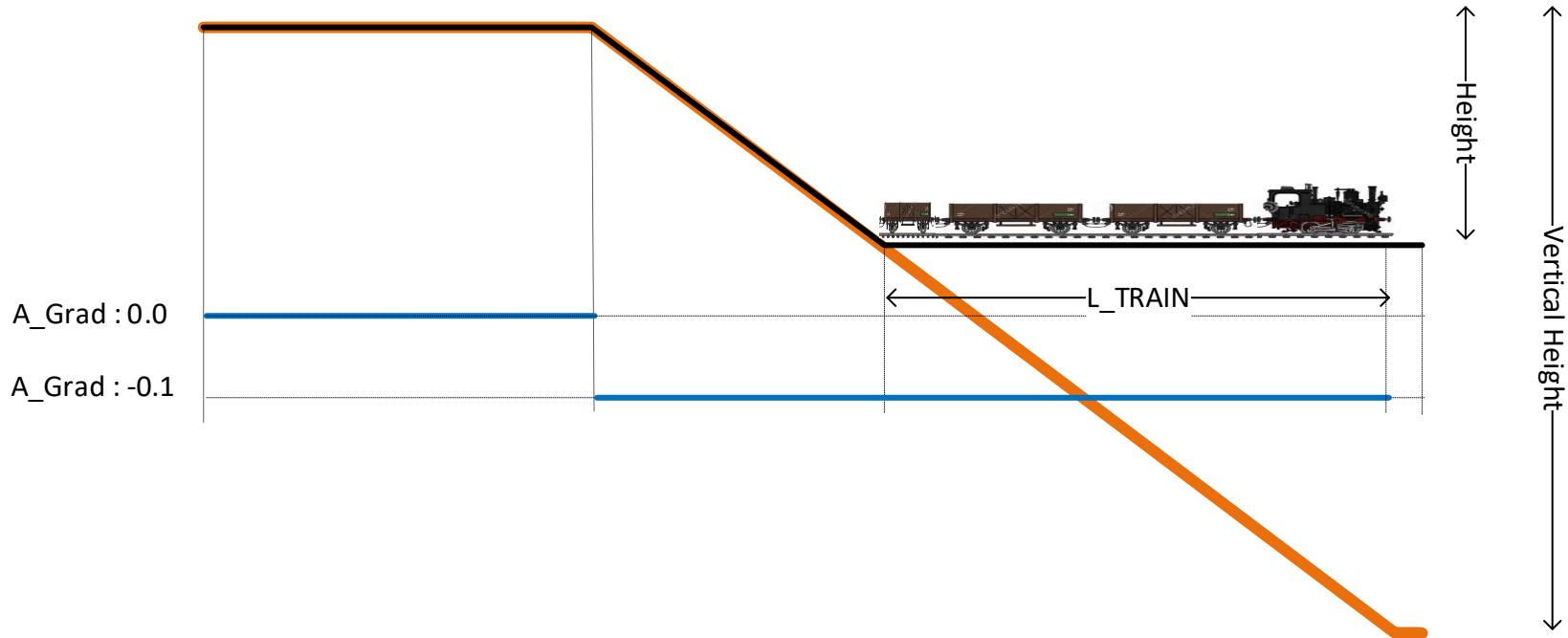


- ERTMS Gradients segments up/down/flat (promille ‰)

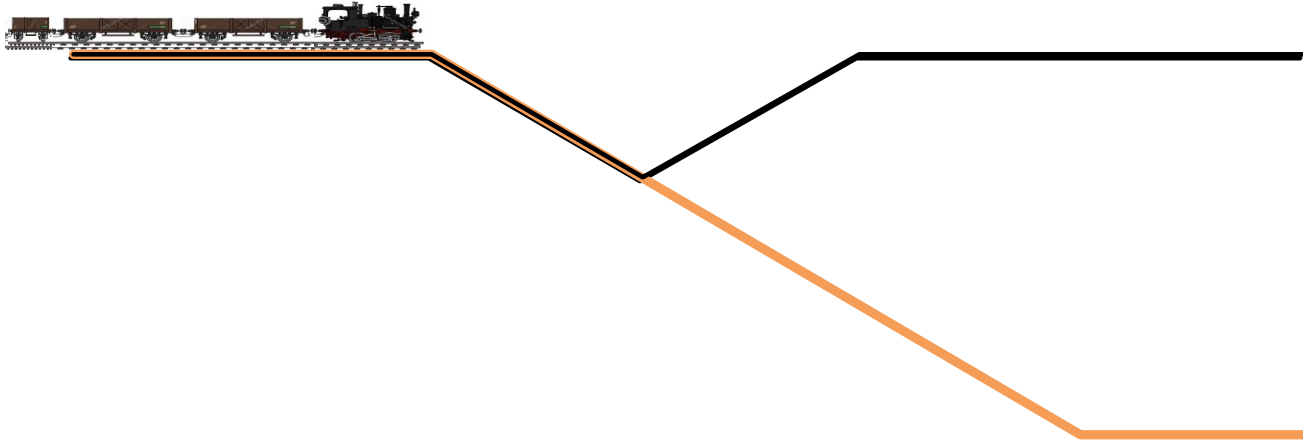
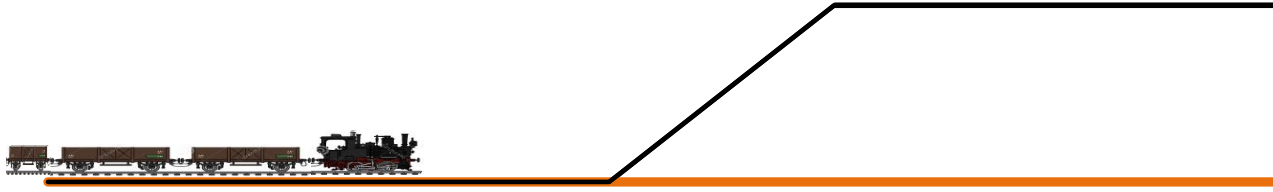


Curved segments
=> Guideline ERTMS.be

ERTMS takes train length into account S026-3.13.4

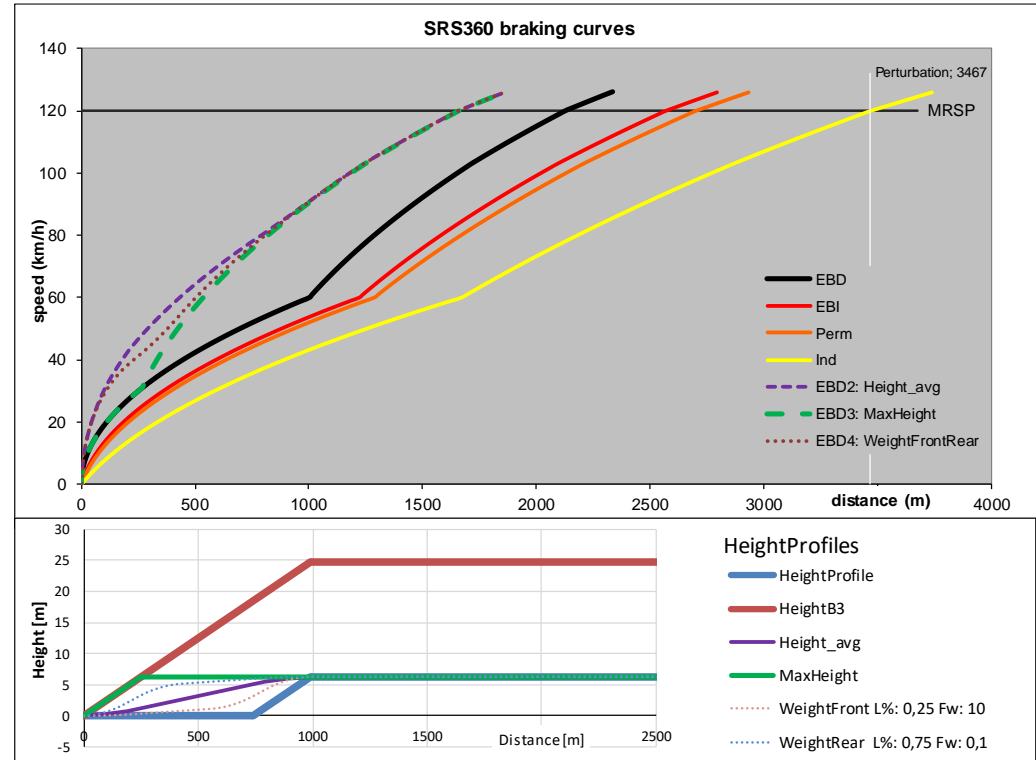


Other examples on 'virtual' height profile for the train



Impact on the brake curve 1

- Cargo train 750m, BWP70%
- Short slope 250m 25 ‰
- (e.g. flyover)
- EBD 490m increased
- Headway increases 14 sec



CR874: Gradient calculation under the train

- Use actual weight distribution to calculate $a_{\text{gradient}}(d)$
 - Train sets fixed configuration or load measurement
 - Cargo trains with DAC: wagon load available
- Limited to maximum unevenly weight distribution factor
 - To be developed improved 'worst-case' calculation

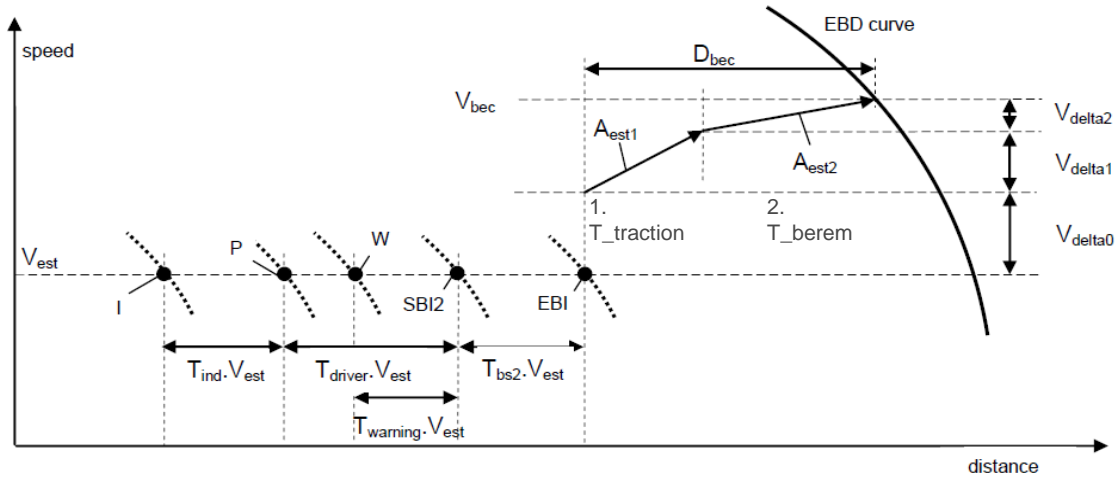


Figure 45: Braking to target supervision limits from EBD curve

CR1435 Gradient for the brake build-up time

CR1435 Gradient for the brake build-up time

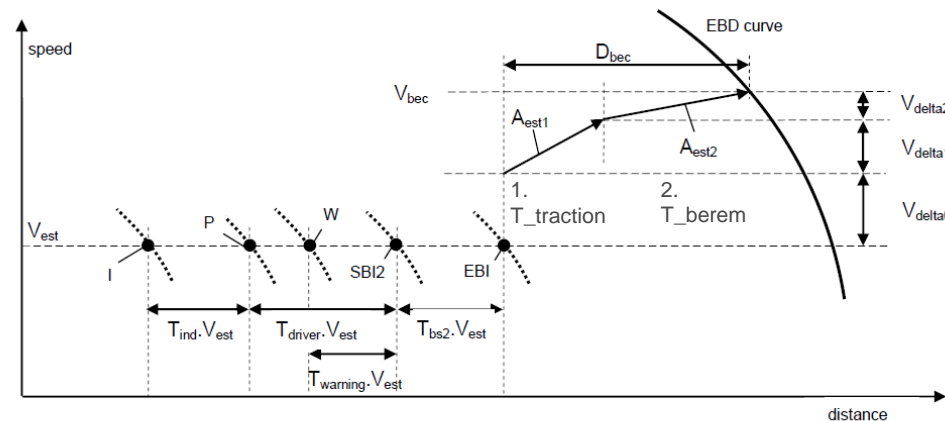


Figure 45: Braking to target supervision limits from EBD curve

Current:

1. $A_{est1} = \text{MAX}(0, A_{est})$;
 2. $A_{est2} = \text{MIN}(A_{est1}, 0.4)$;
- Where 0.4 max gradient downhill.

UNSIG proposal:

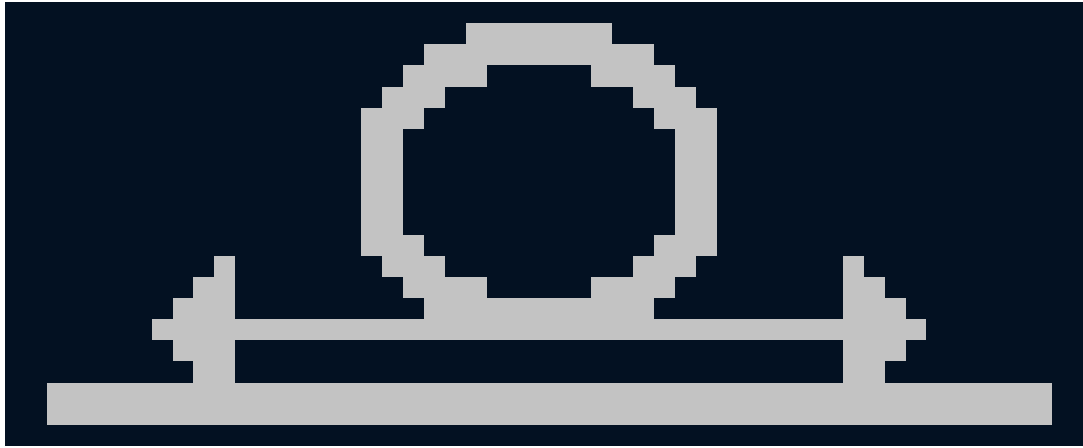
1. $A_{est1} = \text{MAX}(-A_{\text{gradient_min}}, A_{est})$;
2. $A_{est2} = -A_{\text{gradient_min}}$;

EUG proposal:

1. $A_{est1} = A_{est}$;
2. $A_{est2} = \text{MIN}(A_{est}, -A_{\text{gradient_min}})$;

where

$A_{\text{gradient_min}}$ is the minimum value of A_{gradient} within D_{bec} distance calculated as per SUBSET-026 cl. 3.13.4.3.2.
 A_{est} measured acceleration



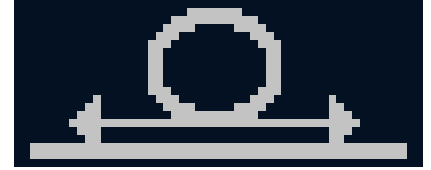
CR1343: Handling reduced adhesion

ProRail



CR1343: Handling reduced adhesion

- Reduced adhesion activated by
 - Driver (button) (if allowed by N.V. Q_NVDRIVER_ADHES)
 - Trackside : adhesion factor (slippery / non slippery rail)
 - Maximum deceleration limited to N.V. A_NVMAXREDADH1/2/3
 - Default value 0.7 / 1.0
- BUT
 - Many countries do not use this function:
 - i.e. driver responsible
 - How done with ATO GOA3/4 (but also GOA2?)
 - Maximum deceleration depends on available adhesion and brake system
 - I.e. worst-case value e.g. 0.4 m/s^2 would not allow normal operation



ATO/ ETCS adhesion management

ATO:

- Adhesion is measured and reported
- ADS (Adhesion Measurement system)
- Adhesion category (ADH)
- Adhesion is used in journey profile
- EJRU Flagship 2 WP17

ETCS:

- Adhesion profile (pck71) with Adhesion category
- Onboard adapts brake curve

