

### **ERTMS/ETCS**

# Failure Modes and Effects Analysis for TIU in Application Level 1 and Level 2

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Company	Technical Approval	Management approval
ALSTOM		
ANSALDO		
AZD		
BOMBARDIER		
CAF		
SIEMENS		
THALES		



## 1. MODIFICATION HISTORY

Issue Number Date	Section Number	Modification / Description	Author
0.0.1. 16/03/01	ALL	Creation	S. Chassard
0.0.2 26/02/02	5	Revised after comments and to achieve consistency with subset 88	SCH
2.0.0.	3.1.1.2.	Raised in issue for release to the EEIG.	WLH
2.2.2.		Final release after amendment to reflect the comments in the final report from the ISA's version 1.1 dated 07-03-03 as proposed via the Unisig consolidated review comments on the ISA report v 0.0.2 March 03.	WLH
3.0.0	ALL	Update to SRS Baseline 3.3.0	C. Latorre (MERMEC)
3.0.1	ALL	Update followed to RAMS WG meeting of 03-04 July 2012 (Stockholm)	C. Latorre (MERMEC)
3.0.2	ALL	Update followed to RAMS WG comments	C. Latorre (MERMEC)
3.0.3	ALL	Update followed to RAMS WG conf call meeting of 09 October 2012 (see MoM 'RAMS Meeting nr 2012:10 – telecon 2012-10-09').	C. Latorre (MERMEC)
3.0.4	<ul> <li>Footer of the first section.</li> <li>5.4.1.4.</li> <li>Chapter 8.</li> <li>5.4.1.1.</li> </ul>	Some editorial changes. Comments from NK and JPG have been considered in 5.4.1.1.	C. Latorre (MERMEC)
3.0.5	<ul> <li>FMEA ref. Id. 5.6.1,</li> <li>5.6.2, 5.4.1.4, 5.3.1.1,</li> <li>5.3.2.1, 5.3.3.1,</li> <li>5.3.4.1, 5.3.5.1,</li> <li>5.3.7.1, 5.3.8.1.</li> <li>Chapter 7.</li> </ul>	Update followed to TIU Safety Group's comments reported in MoM 'RAMS Meeting nr 2012:11 – Madrid 2012-10-25/26' v002.	C. Latorre (MERMEC)



	- Section 5.2.6.		
	- Table 4.		
3.0.6	- FMEA ref. ld. 5.4.2.8	Comments on S-080 v3.0.5 from	C. Latorre
	- 5.2.6.1	JPG have been considered.	(MERMEC)
	- FMEA ref. ld. 5.3.6.2		
	- FMEA ref. ld. 5.4.1.7		
	- FMEA ref. ld. 5.4.2.8		
	- FMEA ref. ld. 5.6.5		
	- FMEA ref. ld. 5.6.10		
	- section 7.1.2		
3.0.7	- FMEA ref. ld. 5.1.1.2	Comments on S-080 v3.0.6 from	C. Latorre
	- section 5.2.3.2	TIU Safety Group.	(MERMEC)
	- FMEA ref. ld. 5.3.9.1 (TCO)		
	<ul> <li>section 7.1.3</li> <li>(Assumption for TCO)</li> <li>FMEA ref. Id. 5.1.2.1</li> <li>FMEA ref. Id. 5.1.3.2</li> </ul>		
	- FIMEA ref. Id. 5.6.1		
200	- FINEA ref. Id. 5.0.2	Analysis modified as some systems	C. L atarra
3.0.8	- FMEA ref. ld. 5.2.2.2 - Added section 7.1.4 'Brake Pressure'	of SG's answer about Service Brake application's feedback.	(MERMEC)
3.0.9	<ul> <li>- 5.2.3.2</li> <li>- 5.2.3.3</li> <li>- section 5.2.6</li> <li>- section 5.2.7</li> <li>- Section 5.3.6</li> <li>- Section 5.4.3</li> <li>- Inserted new row in FMEA for 'Train data – Other International Train Categories' (section 5.6)</li> <li>- inserted FMEA Id 5.6.3</li> <li>- update FMEA id 5.6.5</li> </ul>	Emergency Brake Command Feedback and Status noted as to be deleted from the analysis since not more considered in current S- 034 version. Updated Special Brake Status Analysis and Additional Brake Status due to S-034 modification. Passenger Door output has been renamed to Station Platforms according to current S-034 version The FMEA row of Train Integrity input has been removed since according to S-034 the input has to be harmonized.	C. Latorre (MERMEC)



	- update FMEA id 5.6.6	Inserted Analysis for Train data -	
	- updated chapter 6 for	Other International Train	
	S-034 references	Categories.	
	- updated chapter 7	Updated analysis for Train data -	
		traction/brake parameters	
		(consistency with S-120)	
		Updated analysis for Train data –	
		(consistency with S-120)	
		Added application constraints in Conclusion Chapter for:	
		Special Brake Status Input	
		Station Platforms Input	
		<ul> <li>Train Data – Maximum Train Speed</li> </ul>	
		• Train Data –	
		Traction/Brake parameters	
3.0.10	ALL	Update to SRS Baseline 3.3.1	C. Latorre
			(MERMEC)
3.0.11		Updated during RAMS-meeting	DARI
3.0.12		Baseline 3 1 <sup>st</sup> maintenance	DARI, F.
2014-10-27		release version	Bitsch
3.1.0		Modifications due to CR239,	C. Latorre
		CR539, CR1163, CR1258	(MERMEC)
		Rejection	
3.1.1		Chnges from	C. Latorre
		080v3 1 0 v1 0 review and	
		comments from CAF (AV)	
3.1.2	5.5 Editorial change to	Editorial change to FMEA Ref Id	C. Latorre
	FMEA Ref Id	Added a clause to section	(MERMEC)
	7.1.1	'Conclusion – Application	
		Constraint' 7.1.1	
3.1.3		After RAMS meeting (2016:02)	C. Latorre
	FMEA 5.5.2.1 and	discussion, the analysis have	(MERMEC)
	5.5.2.2	been updated in:	
	FMEA 5.5.2.9	- Train Data - Train Category (Cant	
	Clause 7.1.1.8	Deficiency)	



		<ul> <li>Train Data - Traction system(s) accepted by the engine -&gt; change in Mode Field</li> <li>Internal Barrier -&gt; Driver validation according specific project</li> </ul>	
3.1.4	FMEA 5.2.6.1 FMEA 5.4.1.3 FMEA 5.5.2.2 FMEA 5.5.2.4 FMEA 5.5.2.9 FMEA 5.5.2.10 Table 1 FMEA 5.3.4.1 FMEA 5.4.1.4 Clause 7.1.1.6 Chapter 8	<ul> <li>Change following comments received from CAF.</li> <li>Change following comments received from THALES.</li> <li>Severity in 5.4.1.4 changed to catastrophic after CAF comment</li> <li>Clause 7.1.1.6 reports new assumption of FMEA 5.4.1.4</li> <li>Chapter 8: TI-6a deleted from the item list of the note</li> </ul>	C. Latorre (MERMEC)
3.1.5	FMEA 5.4.1.4 Clause 7.1.1.6 Chapter 8	<ul> <li>Severity in 5.4.1.4 changed to RAM Issue after RAMS Meeting discussion</li> <li>Clause 7.1.1.6 reports assumption of FMEA 5.4.1.4</li> <li>Chapter 8: TI-6a deleted</li> </ul>	C. Latorre (MERMEC)
3.1.6 3.2.0 2016-06-20	Chapter 8 No change	Minor change due to RAMS WG comments Baseline 3 2 <sup>nd</sup> release version	C. Latorre (MERMEC) RAMS WP



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## 3. INTRODUCTION

The purpose of this document is to provide an FMEA (Failure Modes Effects Analysis) for the ERTMS onboard interface with train in ERTMS application level 1 and in level 2.

The inputs documents used as a basis for this study are:

- [Ref. 1] UNISIG: SUBSET-026, UNISIG SRS, issue 3.6.0
- [Ref. 2] UNISIG: SUBSET-034, FIS for the Train Interface, issue 3.2.0
- [Ref. 3] ERA: ETCS Driver Machine Interface ERA\_ERTMS\_015560, issue 3.5.0
- [Ref. 4] UNISIG: SUBSET-035, Specific Transmission Module FFFIS, issue 3.2.0
- [Ref. 5] UNISIG: SUBSET-077, Causal Analysis Process; issue 3.0.0.

This analysis is based on the reference architecture provided in SUBSET-026 Chapter 2.

Failures in Level NTC (e.g. regarding output 'Special Brake inhibit / Pantograph / Air tightness / Main Power Switch – STM Order', input 'National System Isolation', and input 'Train Data - List of National Systems available on-board') are excluded from this analysis since it is only applicable to Level 1 and Level 2.



### 4. ASSUMPTIONS

- 4.1.1.1 The functions analysed in this document are those specified in the FIS TIU [Ref. 2] and listed in chapter 2 of the same document.
- 4.1.1.2 Failures identified as leading to a RAM issue are not developed further.
- 4.1.1.3 Special Braking orders and status are handled as a whole no matter which type of brake is applied (eddy current brake, regenerative brake, magnetic shoe brake, etc.).
- 4.1.1.4 The Traction Status input has been excluded from this analysis since the effects related to its failures depend by the use made of Traction Status information by STM in level NTC.



## 5. FMEA

This FMEA study has been conducted according to FMEA process defined in SUBSET-077 [Ref. 5].

Deviating from the FMEA definition in SUBSET-077, the column Event-ID replaces the former one named as "Failure Rate" (originally in FMEA template). This column will be used to provide the link of all failure effects to TI-XX hazardous events in SUBSET-091 (ETCS Core Hazard coverage).

#### 5.1 Mode Control

#### 5.1.1 Sleeping

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	Failure Effects		ETCS External Protection/ Mitigation/	evrity	Event-ID	Internal barriers	
Ľ.					Local	Intermediate	Initial End Effect	Barriers	۶e		
1.1.1	Sleeping Command information (SLEEPING REQUESTED/SL	Absent Incorrect Failure to report	- TIU Failure - ETCS onboard failure	SB, PS	"Sleeping requested" state is not provided to board	On-board ETCS does not know if it has to go to sleeping	On-board remains in SB, PS mode		l Issue		
5.	EEPING NOT REQUESTED)	"sleeping requested"	other than TIU						RAN		



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	Failure Effects			ETCS External 2: Protection/ 5 Mitigation/ 5		Event-ID	t-ID Internal barriers
8					Local	Intermediate	Initial End Effect	Barriers	Se		
5.1.1.2		Incorrect Insertion Inappropriate selection of "Sleeping requested"	- TIU Failure - ETCS onboard failure other than TIU	SB	"Sleeping requested" state unduly selected during normal operation	Loss of Standstill protection	Exceedance of safe speed or distance as advised to ETCS	Operational rule: Driver has to ensure the standstill before closing the cab.	Catastrophic	TI-3	
5.1.1.3		Incorrect Insertion Inappropriate selection of "Sleeping requested"	- TIU Failure - ETCS onboard failure other than TIU	PS	Sleeping unduly selected during normal operation	-	On-board transits in SL mode		RAM issue		Vehicle must be at "standstill"
5.1.1.4		Incorrect Insertion Failure to maintain "Sleeping requested" state	- TIU Failure - ETCS onboard failure other than TIU	SL	"Sleeping requested" state deactivated prematurely	ETCS OB switches to SB mode	Leading Engine cannot proceed. In case of leaving a tunnel (leading engine in mode RV) then reverse movement will not be possible if the slave engine is in mode SB.		marginal	TI-3	Transition to SB mode is not possible if vehicle is not at standstill. The engine is remote controlled by the leading engine (Subset-026, 4.4.6.1.3).



#### 5.1.2 Passive Shunting

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/	erity	Event-ID	Internal barriers
Ľ					Local	Intermediate	Initial End Effect	Barriers	Š		
5.1.2.1	Passive shunting information (PASSIVE SHUNTING PERMITTED/PAS SIVE SHUNTING NOT PERMITTED)	Incorrect Insertion Inappropriate selection of "Passive shunting permitted"	- TIU Failure - ETCS onboard failure other than TIU	SH	"Passive shunting permitted" information is provided to On- board ETCS when not required	At desk closure, On-Board ETCS switches in PS Mode instead of SB. Standstill supervision function no	Exceedance of safe speed or distance as advised to ETCS	Driver has to ensure the standstill (e.g. by applying the parking brake before leaving the cab).	Catastrophic	TI-7	"Continue Shunting on desk closure" function is active.



#### 5.1.3 Non-Leading

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	Failure Effects			ETCS External Protection/ Mitigation/ Barriers	sverity	Event- ID	Internal barriers
œ					Local	Intermediate	Initial End Effect	Burners	Š		
5.1.3.1	Non-Leading information (NON LEADING PERMITTED – NON LEADING NOT PERMITTED)	Absent Incorrect Failure to report "Non Leading permitted"	- TIU Failure - ETCS onboard failure other than TIU	SB, SH, FS, LS, SR, OS	"Non Leading permitted" information is not provided to On-board ETCS	On-board ETCS is not allowed to switch in NL mode and remains in the current mode. Train supervision functions active according to the current mode.	ETCS On-board equipped on non leading engine can command EB during Non- Leading Engine movement.	Driver shall expect the transition to NL mode before moving Non Leading Engine.	RAM issue		
5.1.3.2		Incorrect Insertion Inappropriate selection of "Non Leading permitted"	- TIU Failure - ETCS onboard failure other than TIU	SB, SH, FS, LS, SR OS,	"Non Leading permitted" information is provided to On-board ETCS when not required	On-board ETCS switches to NL mode after driver selection when not required. Loss of supervision.	Exceedance of safe speed or distance as advised to ETCS.	New mode is displayed on the DMI. Driver is not going to leave the cab.	Catastrophic	TI-8	Driver selects NON LEADING on DMI and Vehicle is at standstill
5.1.3.3		Incorrect Insertion Failure to maintain "Non Leading permitted"	- TIU Failure - ETCS onboard failure other than TIU	NL	"Non Leading not permitted" information provided to On-board ETCS when not required	On-board ETCS switches to SB mode when not required activating standstill supervision	Vehicle cannot proceed		RAM issue		Vehicle is at standstill



#### 5.1.4 Isolation

tef ID	Macro Function Data Item	Failure Mode	e Failure ( Cause	lure Operation use al Mode	Failure Effects			ETCS External Protection/ Mitigation/	sverity	Event- ID	Internal barriers
Ľ.					Local	Intermediate	Initial End Effect	Barriers	Š		
5.1.4.1	Isolation output (ETCS ISOLATED/ETCS NOT ISOLATED)	Absent incorrect Failure to transmit ETCS ISOLATED state to the vehicle	- TIU Failure - ETCS onboard failure other than TIU	IS	Information received by vehicle is "ETCS OBU not isolated" but ETCS OBU is isolated	Related to the function for which the output information is used for. No effect on ETCS supervision	-		RAM Issue		
5.1.4.2		Incorrect Insertion Faulty Transition to ETCS ISOLATED state	- TIU Failure - ETCS onboard failure other than TIU	All Modes	Information received by vehicle is "ETCS OBU isolated" but ETCS OBU is not isolated.	DMI continues displaying current mode information.	-	The driver knows when the OBU is isolated and will be informed of the isolation mode.	RAM Issue		Isolation status must be shown to the driver (Subset 026 4.4.3.1.2).



#### 5.2 Control of Brakes

#### 5.2.1 Service Brake Command

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/ Barriers	verity	Enent- ID	Internal barriers
Ř					Local	Intermediate	Initial End	Damers	Se		
5.2.1.1	Service Brake command (SERVICE BRAKE COMMANDE D / SERVICE BRAKE NOT COMMANDE D)	Absent Incorrect Failure to Command Brake Application when required	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS	SB application command (SERVICE BRAKE COMMAND ED state) not transmitted to the vehicle	SB Not activated when required. Emergency Brake application when passing the EBI limits or before any other critical situation in all cases where EBI limits protect the train. In situations where EBI limits are not active (e.g. Protection against undesirable movements Subset- 026, 3.14) EB is applied as consequence of the SB application failure (Subset-026, 3.14.1.2).	Vehicle at standstill after EB has been applied	Application Constraints: If the ETCS Onboard is implemented using Service Brake to protect the train against undesirable movements, then a project specific safety analysis is needed in order to show that the failure of this signal is recognized and the EB is applied as safeguarding.	RAM Issue		Subset-026, 3.14.1.2: "In case only the application of (the non-vital) service brake has been commanded and the service brake fails to be applied, the emergency brake command shall be given."



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/ Barriers	verity	Enent- ID	Internal barriers
ñ					Local	Intermediate	Initial End	Barriers	Se		
5.2.1.2		Incorrect Insertion Faulty Transition to SERVICE BRAKE COMMANDED state	- TIU Failure - ETCS onboard failure other than TIU	All modes	SB application command (SERVICE BRAKE COMMAND ED state) transmitted to the vehicle while not required	SB activated when not required	Vehicle unduly braked		RAM Issue		



#### 5.2.2 Brake Pressure

	Macro Function	acro Failure Mode Failure Iction Cause		Operat ional		rat Failure Effects		ETCS External Protection/	ity	Event- ID	Internal barriers
Ref I	Data Item			Mode	Local	Intermediate	Initial End Effect	Mitigation/ Barriers	Sever		
5.2.2.1	Brake Pressure	Absent Incorrect Insertion Failure to report Brake Pressure information	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV, SH, SN	Wrong Brake Pressure information sent on- board	<ol> <li>Erroneous Brake</li> <li>Pressure state used in the service brake feedback model by</li> <li>ETCS-OBU. T_bs1 and T_bs2 (service brake build up time) misjudged due to erroneous input.Calculated T_bs less than expected implies wrong calculation of SBI location.</li> <li>In case Brake</li> <li>Pressure input is used as Service Brake feedback, erroneous brake pressure could lead to consider the service brake erroneously applied.</li> <li>In case Brake</li> <li>Pressure input s not used as Service Brake</li> </ol>	1) and 2) Service Brake will be applied later than required. Emergency Brake application when passing the EBI limits or before any other critical situation. Vehicle at standstill after EB has been applied in all cases where EBI limits protect the train. In situations where EBI limits are not active (e.g. Protection against undesirable movements Subset-026, 3.14) if OBU uses service brake to stop the train and brake pressure as brake feedback, the loss of train undesirable movement protection occurs in case of failure to service brake.	Application Constraint: If the ETCS Onboard is implemented using Service Brake to protect the train against undesirable movements and the Brake Pressure signal is used as Service Brake feedback, then a project specific analysis is needed in order to show that the failure of the signal has acceptable safety consequences.	RAM Issue		Independent failure to service brake output.



#### 5.2.3 Emergency Brake Command

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects Local Intermediate Initial End Effect			verity	EVENT ID	Internal barriers
8					Local	Intermediate	Initial End Effect	Barriers	Se		
5.2.3.1	Emergency Brake command (EMERGENC Y BRAKE COMMANDE D / EMERGENCY BRAKE NOT COMMANDE D)	Absent Incorrect Failure to Command Emergency Brake Application when required	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS	EB application command (EMERGENCY BRAKE COMMANDED state) not transmitted to the vehicle	EB Not activated when required	Exceedance of safe speed or distance as advised to ETCS	Product specific safeguarding	Catastrophic	TI-1	
5.2.3.2		Insertion Incorrect Brakes Application Commanded when not required	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS	EB application command (EMERGENCY BRAKE COMMANDED state) transmitted to the vehicle while not required	EB activated when not required	Vehicle incorrectly brought to stand- still		RAM Issue		



#### 5.2.4 Special Brake Inhibition Area – Trackside Orders

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operatio nal Mode		Failure Effe	cts	ETCS External Protection/ Mitigation/ Barriers	verity	EVENT ID	Internal barriers
8					Local	Intermediate	Initial End Effect	Dainers	эS		
5.2.4.1	<ul> <li>Special Brake</li> <li>Inhibition Area –</li> <li>Trackside Order</li> <li>the remaining distance from the max safe front end of the train to the start location of this special brake inhibition area</li> <li>the remaining distance from the min safe rear end of the train to the end location of this special brake inhibition area</li> </ul>	Absent Incorrect Failure to the informatio n output leading to not request Special Brake inhibition when required	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS	Special Brake inhibition request not transmitted to the vehicle when required	Special Brake not inhibited although required by trackside. Special Brake Status informs OBU that Special Brake is not inhibited.	Special Brake are erroneously applied when EB/SB are requested, in a section where they should not be used. Possible damages to trackside infrastructure (e.g. to the tracks).		Baue RAM Issue		



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operatio nal Mode		Failure Effe	cts	ETCS External Protection/ Mitigation/ Barriers	verity	EVENT ID	Internal barriers
R					Local	Intermediate	Initial End Effect	Darriers	Se		
5.2.4.2		Insertion Incorrect Failure to the informatio n output leading to request Special Brake inhibition when not required	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, SH, SB, RV	Special Brake inhibition request transmitted to the vehicle when not required	Special Brake inhibited although not required by trackside. Special Brake Status informs OBU that Special Brake is inhibited. OBU updates SB/EB braking curves according to current special	Emergency Brake applied by the vehicle before than expected by ETCS-OBU		RAM Issue		
						brake status.					



#### 5.2.5 Special Brake Inhibit – STM Orders

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/	iverity	EVENT ID	Internal barriers
œ					Local	Intermediate	Initial End Effect	Barriers	۶۶		
5.2.5.1	Special Brake Inhibit – STM Order (NOT INHIBITED/IN HIBITED)	Absent Incorrect Failure to Request Special Brake inhibition when required	- TIU Failure - ETCS onboard failure other than TIU	SN	Special Brake inhibition request (INHIBITED state) not transmitted to the vehicle when required	Special Brake not inhibited although required by trackside. Special Brake Status informs OBU that Special Brake is not inhibited.	Special Brake are erroneously applied when EB/SB are requested, in a section where they should not be used. Possible damages to trackside infrastructure (e.g. to the tracks).		RAM Issue		

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ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/	verity	EVENT ID	Internal barriers
₽£					Local	Intermediate	Initial End Effect	Barriers	Se		
5.2.5.2		Insertion Request Special Brake inhibition when not required	- TIU Failure - ETCS onboard failure other than TIU	SN	Special Brake inhibition request (INHIBITED state) transmitted to the vehicle when not required	Special Brake inhibited although not required by trackside. Special Brake Status informs OBU that Special Brake is inhibited. OBU updates SB/EB braking curves according to current special brake status.	Emergency Brake applied by the vehicle before than expected by ETCS-OBU		RAM Issue		



#### 5.2.6 Special Brake Status

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/ Barriers	verity	Event ID	Internal barriers
Ř					Local	Intermediate	Initial End Effect		Se		
5.2.6.1	Special Brake Status (SPECIAL BRAKE ACTIVE/S PECIAL BRAKE NOT ACTIVE)	Absent Incorrect Insertion The input wrongly reports to ETCS- OBU that Special Brake is not active when actually it is	- TIU Failure - ETCS onboard failure other than TIU	FS,LS,SR, OS,UN	Status Information of SPECIAL BRAKE ACTIVE is not transmitted to ETCS-OBU when required or delayed	The braking curve used by ETCS- OBU assumes an Emergency Brake Capability lower than the actual. Wrong status on the DMI.	Emergency Brake applied by ETCS-OBU before than expected.	Driver knows the real status of Special Brake	RAM Issue		
5.2.6.2		Incorrect Insertion The input wrongly reports to ETCS- OBU that Special Brake is active when actually it is not	- TIU Failure - ETCS onboard failure other than TIU	FS,LS,SR, OS,UN	Special Brake Status is inappropriately reported as active to ETCS- OBU when actually it is not	Emergency Brake Capability less than assumed by ETCS Brake model, wrong curve calculation. Failure to display brake status to driver.	Evaluation of potential effect on safe speed and distance supervised is project specific	Application Constraint: If using Special Brake as available and affecting the Emergency Brake curve, the failure of the input 'Special Brake status' could have catastrophic safety severity. A project specific safety analysis is required.	Hint: Evaluation not in this Subset		



#### 5.2.7 Additional Brake Status

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/	everity	Event-ID	Internal barriers
Ľ					Local	Intermediate	Initial End Effect	Barriers	Š		
5.2.7.1	Additional Brake Status (ADDITIONAL BRAKE ACTIVE/ADDI TIONAL BRAKE NOT ACTIVE)	Same analysis as described in 5.2.6									



#### 5.3 Control of Train

#### 5.3.1 Change of Traction System (CTS)

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operat ional Mode		Failure Effects		ETCS External Protection/	verity	Event-ID	Internal barriers
θ					Local	Intermediate	Initial End Effect	Barriers	es		
	Change Of Traction	Deletion Corruption	- TIU Failure	All modes	The Change of Traction System	Traction System does not	Vehicle is fed with a non-appropriate	Vehicle should be			Change of traction system is announced and
	System	Repetition Insertion	- ETCS onboar d		information is not properly	required or changes when	Possible damage to infrastructure	protection systems.	Ø		the DMI (S-026 §5.18.10)
5.3.1.1		The output information used to change the Traction System is erroneous or missing or delayed so that the traction system will not be changed when required	failure other than TIU		transmitted to the vehicle so that the vehicle will not execute the change of traction when required	not required.		Driver should be able to control the pantograph manually.	RAM Issue		



#### 5.3.2 Powerless section with pantograph to be lowered – Trackside orders

lef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operat ional Mode		Failure Effects		ETCS External Protection/ Mitigation/	evrity	Event-ID	Internal barriers
Ľ.					Local	Intermediate	Initial End Effect	Barriers	š		
	Powerless	Deletion	- TIU	All	The Pantograph	Pantograph	No Power to	Driver should			Powerless section with
	section with	Corruption	Failure	modes	<ul> <li>Trackside</li> </ul>	lowered/raised	traction unit	be able to			pantograph to be lowered
	pantograph to	Delay	- ETCS		output orders	when not		control the			is announced and
	be lowered –	Repetition	onboard		used to lower	required		pantograph			indicated to the driver on
	Trackside	Insertion	failure		the pantograph			manually.			the DMI (S-026 §5.18.2)
	orders		other than		is not properly						
		The output	TIU		transmitted to				ē		
5		information used to			the vehicle so				SSL		
ŝ		lower the pantograph			that the vehicle				Σ		
ŝ		is erroneous or			will not				RA		
		missing or delayed			lower/raise the						
		so that the			pantograph						
		pantograph will be			when required						
		not in the									
		lowered/raised status									
		when required									



#### 5.3.3 Pantograph – STM Order

Ref ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects				Event-ID	Internal barriers
8					Local	Intermediate	Initial End Effect	Barriers	Se		
5.3.3.1	Pantograph – STM Order	Deletion Corruption Delay Repetition Insertion Insertion The output information used to lower the pantograph is erroneous or missing or delayed so that the pantograph will be not in the lowered/raised status when required	- TIU Failure - ETCS onboard failure other than TIU	SN	The Pantograph – Trackside output orders used to lower the pantograph is not properly transmitted to the vehicle so that the vehicle will not lower/raise the pantograph when required	Pantograph lowered/raised when not required	No Power to traction unit	Driver should be able to control the pantograph manually.	RAM Issue		Assumption for STM: Powerless section with pantograph to be lowered is announced and indicated to the driver on the DMI (compare S-026 §5.18.2)



#### 5.3.4 Air tightness area– Trackside orders

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operat ional Mode		Failure Effects		ETCS External Protection/ Mitigation/	verity	EVENT ID	Internal barriers
Å					Local	Intermediate	Initial End Effect	Barriers	Se		
5.3.4.1	Air Tightness area – Trackside Order	Deletion Corruption Delay The output information used for commanding the flaps closure is erroneous or missing or delayed so that the Air Conditioning intake will be open when not required	- TIU Failure - ETCS onboard failure other than TIU	All modes	The output information used for commanding the flaps closure is not properly transmitted to the vehicle so that the vehicle will not close the flaps when required	Air Conditioning intake not closed when required	Passenger could be affected by sudden change of pressure or noxious air coming inside train	Driver should be able to control the air conditioning intakes manually.	Critical	No relation to ETCS Core hazard	Air tightness area is announced and indicated to the driver on the DMI (S-026 §5.18.6).



ef ID	Macro Function Data Item	Failure Mode	ailure Mode Failure Operat Cause ional Mode			Failure Effects		ETCS External Protection/ Mitigation/		EVENT ID	Internal barriers
Å					Local	Intermediate	Initial End Effect	Barriers	Se		
5.3.4.2		Corruption Repetition Insertion The output information used for commanding the flaps closure is erroneous so that the Air Conditioning intake will be closed when not required	- TIU Failure - ETCS onboard failure other than TIU	All modes	The output information used for commanding the flaps closure is not properly transmitted to the vehicle so that the vehicle will close the flaps when not required	Air Conditioning intake closed when not required	Unfavourable climate condition inside the train	Driver should be able to control the air conditioning intakes manually.	RAM Issue		



#### 5.3.5 Air tightness – STM Order

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/		Event ID	Internal barriers
~					Local	Intermediate	Initial End Effect	Barriers	Se		
5.3.5.1	Air tightness – STM Order	Deletion Corruption Delay The output information used for commanding the flaps closure is erroneous or missing or delayed so that the Air Conditioning intake will be stay open when not required	- TIU Failure - ETCS onboard failure other than TIU	SN	The output information used for commanding the flaps closure is not properly transmitted to the vehicle so that the vehicle will not close the flaps when required	Air Conditioning intake not closed when required	Passenger could be affected by sudden change of pressure or noxious air coming inside train	Driver should be able to control the air conditioning intakes manually.	Critical	No relation to ETCS Core hazard	Assumption for STM: Air tightness area is announced and indicated to the driver on the DMI (compare S-026 §5.18.6).



D	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	Failure Effects			ETCS External Protection/	erity	Event ID	Internal barriers
Rei					Local	Intermediate	Initial End Effect	Mitigation/ Barriers	Sev		
.2		Repetition Insertion The output information used for commanding	- ETCS onboard failure other than TIU		information used for commanding the flaps closure is not properly transmitted to	intake closed when not required	climate condition inside the train	be able to control the air conditioning intakes manually.	ens		
5.3.5		the flaps closure is erroneous so that the Air Conditioning intake will be closed when not required			the vehicle so that the vehicle will close the flaps when not required				RAM I		



#### 5.3.6 Station Platform

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	ation Failure Effects ode Local Intermediate Initial End		ETCS External Protection/ Mitigation/	verity	EVENT ID	Internal barriers	
Ř					Local	Intermediate	Initial End Effect	Barriers	Se		
5.3.6.1	Station Platform	Deletion Corruption Delay The output information 'Station Platform' used for enabling the passenger door is erroneous or missing or delayed so that the passenger door will not be open when required	- TIU Failure - ETCS onboard failure other than TIU	All modes	The output information used for enabling the passenger door is not properly transmitted to the vehicle so that the vehicle will not open the passenger door when requested by the driver	Passenger door opening disabled when not required	Passenger door does not open when externally required	Assumption: The ETCS door opening enabling function is not for safety reasons, e.g. in cases of evacuation. There is an emergency procedure to open the doors.	RAM Issue		
5.3.6.2		Corruption Repetition Insertion The output information of Station Platform used for passenger door enabling is erroneous so that the passenger door opening will be enabled when not allowed	- TIU Failure - ETCS onboard failure other than TIU	All modes	The output information used for enabling is not properly transmitted to the vehicle so that the passenger door opening will be enabled when not allowed	ETCS OBU does not inhibit the opening of passenger door when required	Passengers could be injured / run over when leaving the train.	Doors should be controlled manually by the driver (e.g. independent switches which control each side doors).	Critical	No relation to ETCS Core hazard	



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#### 5.3.7 Powerless section with main power switch to be switched off – Trackside orders

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	Failure Effects E Pro Mit		ETCS External Protection/ Mitigation/	iverity	Event ID	Internal barriers	
œ					Local	Intermediate	Initial End Effect	Barriers	Š		
5.3.7.1	Powerless section with main power switch to be switched off – Trackside orders	Deletion Corruption Delay The output information used to switch off the main power switch is erroneous or missing or delayed so that the main power will not be switched off when required	- TIU Failure - ETCS onboard failure other than TIU	All modes	The output information used to switch off the main power is not properly transmitted to the vehicle so that the vehicle will not switch off the main power when required	Main power switch is not opened where necessary.	Main power switch is not opened in powerless section	Driver should be able to control the main power switch manually.	RAM Issue		Powerless section with main power switch to be switched off is announced and indicated to the driver on the DMI (S-026 §5.18.3).
5.3.7.2		Corruption Repetition Insertion The output information used to Switch Off the main power switch is erroneous so that the main power will be switched off when not required	- TIU Failure - ETCS onboard failure other than TIU	All modes	The output information used to switch off the main power is not properly transmitted to the vehicle so that the vehicle will switched off the main power when not required	Main power switch is opened where not necessary.	Main power switch is opened before or after a powerless section	Driver should be able to control the main power switch manually.	RAM Issue		



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#### 5.3.8 Main Power Switch – STM Order

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects	i .	ETCS External Protection/ Mitigation/	iverity	Event ID	Internal barriers
2					Local	Intermediate	Initial End Effect	Barriers	Se		
5.3.8.1	Main Power Switch – STM Order	Deletion Corruption Delay The output information used to Switch Off the main power switch is erroneous or missing or delayed so that the main power will not be switched off when required	- TIU Failure - ETCS onboard failure other than TIU	SN	The output information used to switch off the main power is not properly transmitted to the vehicle so that the vehicle will not switch off the main power when required	Main power switch is not opened where necessary.	Main power switch is not opened in powerless section	Driver should be able to control the main power switch manually.	RAM Issue		Assumption for STM: Powerless section with main power switch to be switched off is announced and indicated to the driver on the DMI (compare S- 026 §5.18.3).



f ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/	erity	Event ID	Internal barriers
Re					Local	Intermediate	Initial End Effect	Mitigation/ Barriers	Sev		
		Corruption Repetition	- TIU Failure	All modes	The output information	Main power switch is	Main power switch is opened	Driver should be able to			
		Insertion	onboard		used to switch	opened where	before or after a	control the			
			failure other		off the the main	not necessary.	powerless section	main power			
		The output	than TIU		power is not			switch			
		information			properly			manually.			
N		used to			transmitted to				sue		
8.8		Switch Off the			the vehicle so				llse		
5.3		main power			that the vehicle				AN		
		Switch IS			the main newer				£		
		that the main			when not						
		power will be			required						
		switched off			loquilou						
		when not									
		required									



#### 5.3.9 Traction Cut Off

Note that [Ref. 2] mentions the possibility for a TCO command being issued by an STM. This is not considered here.

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effect	S	ETCS External Protection/ Mitigation/ Barriers	verity	Event- ID	Internal barriers
Ϋ́					Local	Intermediate	Initial End Effect		Se		
5.3.9.1	Traction Cut- off (TCO) application command (DO NOT CUT OFF TRACTION/C UT OFF TRACTION)	Absent Incorrect Failure to Command TCO when required	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, SH, SN, RV	TCO application command (CUT OFF TRACTION state) not transmitted to the vehicle when required.	Unable to cut the traction at warning limit	EBI limits are calculated considering incorrect braking / traction model assuming that residual traction has impact on braking distance. Exceedance of safe speed or distance as advised to ETCS.	If the ETCS/ERTMS on- board equipment is configured to T_traction = MAX((T_traction_cut_off - (T_warning + T_bs2)) ; 0) (see Subset-026, section 3.13.9.3.2.3) the failure of this output shall be considered as having a catastrophic safety severity and product specific safeguarding have to be considered. If the ETCS/ERTMS on- board equipment is configured to T_traction = T_traction_cut_off the failure of this output is to be considered as having a RAM severity.	Catastrophic	TI-11	



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effect	S	ETCS External Protection/ Mitigation/ Barriers	verity	Event- ID	Internal barriers
R					Local	Intermediate	Initial End Effect		Se		
5.3.9.2		Insertion Incorrect Request TCO when not required	- TIU Failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS	TCO application command (CUT OFF TRACTION state) transmitted to the vehicle while not required	TCO activated when not required	Vehicle incorrectly held without traction		RAM Issue		



#### 5.3.10 Change of allowed current consumption

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects	Failure Effects		verity	Event- ID	Internal barriers
œ					Local	Intermediate	Initial End Effect	Damers	Se		
	Change Of	Deletion	- TIU	All modes	The output	Allowed Current	Vehicle performs				
	Allowed	Corruption	Failure		information	Consumption	higher current				
	Current	Delay	- ETCS		used to change	do not change	consumption that				
	Consumpti	Repetition	onboard		the	when required	permitted.				
	on	Insertion	failure		Allowed Current		Trackside				
			other than		Consumption is		equipment is shut				
-		The output	TIU		not properly		down.		ne		
10.		information used to			transmitted to				lss		
		change the Allowed			the vehicle so				Μ		
4)		Current Consumption			that the vehicle				R		
		is erroneous or			will not execute						
		missing or delayed			the change						
		so that the Allowed			when required						
		Current Consumption									
		will not be changed									
		when required									

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#### 5.4 Train Status

#### 5.4.1 Cab Status

tef ID	Macro Functio n Data	Failure Mode	Failure Cause	Oper ation al Mod		Failure Effec	ts	ETCS External Protection/ Mitigation/ Barriers	everity	Event- ID	Internal barriers
ις.	nom			e	Local	Intermediate	Initial End Effect	Damoro	Š		
5.4.1.1	Cab status (NOT ACTIVE/ ACTIVE)	Absent Incorrect Failure or delay to report Cab status (cases: 1. CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE')	- TIU Failure - ETCS onboard failure other than TIU	FS, LS, PT OS, NL, UN, SN, RV	No Cab Status information or delayed sent on-board (although one cab is open it is wrongly assumed that no cab is activated).	ETCS OB goes directly to SB mode	Vehicle brakes applied due to standstill supervision.	Driver realises that DMI is off.	RAM Issue		Standstill supervision applies brakes if movement exceeds specified national distance.
5.4.1.2		Absent Incorrect Failure or delay to report Cab status (cases: 1. CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE')	- TIU Failure - ETCS onboard failure other than TIU	SH	No Cab Status information or delayed sent on-board (although one cab is open it is wrongly assumed that no cab is activated).	Inappropriate transition to SB if the function "continue shunting on desk closure" is not active or if passive shunting signal is not received	Vehicle brakes applied due to standstill supervision.	Driver realises that DMI is off.	RAM Issue		



ef ID	Macro Functio n Data	Failure Mode	Failure Cause	Oper ation al Mod		Failure Effec	ts	ETCS External Protection/ Mitigation/ Barriers	verity	Event- ID	Internal barriers
R	nem			e	Local	Intermediate	Initial End Effect	Damers	Se		
5.4.1.3		Absent Incorrect Failure or delay to report Cab status (cases: 1. CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE')	- TIU Failure - ETCS onboard failure other than TIU	SH	No Cab Status information or delayed sent on-board (although one cab is open it is wrongly assumed that no cab is activated).	Inappropriate transition to PS mode if the function "continue shunting on desk closure" is active AND Passive Shunting input signal is received;	Although the PS mode is less restrictive than SH, vehicle will not perform any undesired movement since the passive shunting input shall have the value "Passive shunting permitted" only if a brake is applied (Subset 034 §2.2.2.3.1).	Driver realises that DMI is off and ensures the standstill if necessary (e.g. by applying the parking brake before leaving the cab)	RAM Issue		Passive Shunting signal received and "continue shunting on desk closure" has been selected by Driver from the DMI.



D	Macro Functio	Failure Mode	Failure Cause	Oper ation		Failure Effec	ts	ETCS External Protection/ Mitigation/	rity	Event- ID	Internal barriers
Ref	Item			Mod	Local	Intermediate	Initial End Effect	Barriers	Seve		
5.4.1.4 Ref II	n Data Item	Absent Incorrect Failure or delay to report Cab status (cases: 1. CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE')	- TIU Failure - ETCS onboard failure other than TIU	al Mod e SB	Local No Cab Status information or delayed sent on-board (although one cab is open it is wrongly assumed that no cab is activated).	Intermediate Transition to SL mode if "sleeping" input signal is received and vehicle is at standstill. No more movement protection, unable to apply brakes. Same situation can apply also in SB if both cabs are normally closed (no failure) and sleeping signal is unduly reported to 'Sleeping Requested' (refer to 5 1 1 2	Initial End Effect Vehicle is coupled electrically to a leading engine and will not perform any undesired movement. If it is not coupled no sleeping signal can be transmitted in SB mode. No transition to SL mode is possible under the exported constraint that the vehicle has to ensure that sleeping input is received only if another cab in the train is active (i.e. another train control system (ETCS or national) provides the	Mitigation/ Barriers	RAM Issue		
						TI-3).	train movement).				



ef ID	Macro Functio n Data	Failure Mode	Failure Cause	Oper ation al		Failure Effec	ts	ETCS External Protection/ Mitigation/	/erity	Event- ID	Internal barriers
Re	ltem			Mod e	Local	Intermediate	Initial End Effect	Barriers	Sev		
5.4.1.5		Insertion Incorrect Cab Status Information is received inappropriately as ACTIVE instead of 'NOT ACTIVE' (cases: 1. CAB A 'NOT ACTIVE' / CAB B 'ACTIVE' fails to CAB A 'ACTIVE' / CAB B 'ACTIVE' ACTIVE' fails to CAB A 'ACTIVE' / CAB B 'ACTIVE')	- TIU Failure - ETCS onboard failure other than TIU	SH, FS, LS, SR, PT OS, NL, UN, RV	Incorrect Cab Status transmitted to ETCS OBU so that, both cabs are erroneously assumed to be "activated" (Not admitted condition)	No harmonized reaction if two cabs are reported active at the same time. Assumption for a possible behaviour: Transition to System Failure mode and EB applied.	Vehicle will be at standstill.		RAM Issue		Note: If the assumption for the intermediate reaction is not fulfilled then a project specific analysis is necessary.
5.4.1.6		Incorrect Insertion Cab Status Information is received inappropriately as ACTIVE instead of 'NOT ACTIVE' (cases: 1. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' fails to CAB A	- TIU Failure - ETCS onboard failure other than TIU	SB	Incorrect Cab Status transmitted to ETCS OBU (closed desk is erroneously assumed to be open by the OBU).	The DMI is on.	Vehicle remains at standstill. Start of Mission can proceed; Driver to revalidate or enter Driver ID.		RAM Issue		ETCS standstill protection.



ef ID	Macro Functio n Data	Failure Mode	Failure Cause	Oper ation al		Failure Effec	ts	ETCS External Protection/ Mitigation/	verity	Event- ID	Internal barriers
Å	item			e	Local	Intermediate	Initial End Effect	Barriers	Se		
5.4.1.7		Incorrect Insertion Cab Status Information is received inappropriately as ACTIVE instead of 'NOT ACTIVE' (cases: 1. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' / CAB B 'ACTIVE')	- TIU Failure - ETCS onboard failure other than TIU	SL	Incorrect Cab Status transmitted to ETCS OBU (closed desk is erroneously assumed to be open by the OBU).	Transition to SB. Standstill supervision is activated.	Standstill supervision can lead to inappropriate vehicle braking, Leading Engine cannot proceed. Start of Mission can proceed; Driver to revalidate or enter Driver ID.		RAM Issue		
5.4.1.8		Incorrect Insertion Cab Status Information is received inappropriately as ACTIVE instead of 'NOT ACTIVE' (cases: 1. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' fails to CAB A	- TIU Failure - ETCS onboard failure other than TIU	PS	Incorrect Cab Status transmitted to ETCS OBU (closed desk is erroneously assumed to be open by the OBU).	Undesired transition to SH mode If "Stop Shunting on desk opening" is not stored on- board.	Train Supervision Functions applicable in SH mode can brake the vehicle.		RAM Issue		



ef ID	Macro Functio n Data	Failure Mode	Failure Cause	Oper ation al		Failure Effec	ts	ETCS External Protection/ Mitigation/	verity	Event- ID	Internal barriers
R	nem			e	Local	Intermediate	Initial End Effect	Dairiers	Se		
5.4.1.9		Incorrect Insertion Cab Status Information is received inappropriately as ACTIVE instead of 'NOT ACTIVE' (cases: 1. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'ACTIVE' / CAB B 'NOT ACTIVE' 2. CAB A 'NOT ACTIVE' / CAB B 'NOT ACTIVE' fails to CAB A 'NOT ACTIVE' fails to CAB A	- TIU Failure - ETCS onboard failure other than TIU	PS	Incorrect Cab Status transmitted to ETCS OBU (closed desk is erroneously assumed to be open by the OBU).	Inappropriate transition to SB mode if "Stop Shunting on desk opening" is stored on- board.	Vehicle brakes applied due to standstill supervision; inappropriate vehicle braking.		RAM Issue		



#### 5.4.2 Direction Controller

kef ID	Macro Functio n Data Item	Failure Mode	Failure Cause	Operatio nal Mode		Failure Effects	i	ETCS External Protection/ Mitigation/ Barriers	everity	EVEN T ID	Internal barriers
Ľ.	nom				Local	Intermediate	Initial End Effect	Durriero	Ň		
5.4.2.1	Direction controller position (FORWA RD/NEU TRAL/B ACKWA RD)	Absent Incorrect Direction Controller Position received inappropriately as NEUTRAL instead of 'FORWARD' or 'BACKWARD''	- TIU Failure - ETCS onboard failure other than TIU	SH, FS, LS, SR, OS, UN, PT, RV	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'NEUTRAL' instead of 'FORWARD' or 'BACKWARD')	The RAP shall prevent forward and reverse movements of the vehicle (Subset-026 3.14.2.3).	Movement of the vehicle inhibited by ETCS-OBU.		RAM Issue		
5.4.2.2		Absent Incorrect Direction Controller Position received inappropriately as NEUTRAL instead of 'BACKWARD'	- TIU Failure - ETCS onboard failure other than TIU	FS, LS, OS	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'NEUTRAL' instead of 'BACKWARD')	Inhibition of RV mode switch if Reverse Position of direction controller cannot be reported to ETCS_OBU	Movement Backward inhibited by ETCS-OBU. If danger situation is ongoing, fast reversal movement of a train is not possible	Driver knows which direction is selected. Operational rules.	Marginal		



ef ID	Macro Functio n Data	Failure Mode	Failure Cause	Operatio nal Mode		Failure Effects		ETCS External Protection/ Mitigation/	verity	EVEN T ID	Internal barriers
8	nem				Local	Intermediate	Initial End Effect	Darners	Se		
5.4.2.3		Incorrect Insertion Direction Controller Position received inappropriately as FORWARD or 'BACKWARD' instead of 'NEUTRAL'	- TIU Failure - ETCS onboard failure other than TIU	SH, SR, OS, UN, PT, RV, FS, LS,	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'BACKWARD' or 'FORWARD' instead of 'NEUTRAL')	Rollaway protection is deactivated	Exceedance of the safe speed or distance as advised to ETCS	<ol> <li>Driver (knows which direction is selected)</li> <li>Safety-related function: Rollaway protection and driver's activity control function is supported by Fail- safe Dead-Man Supervision (TSI Loc Pas, chapter</li> <li>Loc Pas, chapter</li> <li>2.9.3.1) or additionally other vehicle side rollaway protection systems</li> <li>The driver has to ensure the standstill before leaving the cab.</li> </ol>	Catastrophic	TI-5	



ef ID	Macro Functio n Data	Failure Mode	Failure Cause	Operatio nal Mode	Failure Effects		ETCS External Protection/ Mitigation/ Barriers	verity	EVEN T ID	Internal barriers	
~	nem				Local	Intermediate	Initial End Effect	Darriers	Se		
5.4.2.4				SB	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'BACKWARD' or 'FORWARD' instead of 'NEUTRAL')	Standstill supervision is active.	-		No effect		
5.4.2.5		Incorrect Insertion Direction Controller Position received inappropriately as FORWARD instead of 'BACKWARD'	TIU Failure - ETCS onboard failure other then TIU	SH, UN, FS, LS, SR, OS, PT, RV	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'FORWARD' while the actual is 'BACKWARD')	roll away protection function will inhibit the backward movement instead of the forward movement	Rolling in a forward slope is possible.	Driver knows which direction is selected.	Catastrophic	TI-5	



tef ID	Macro Functio n Data	Failure Mode	Failure Cause	Operatio nal Mode		Failure Effects		ETCS External Protection/ Mitigation/ Barriers	everity	EVEN T ID	Internal barriers
œ	nem				Local	Intermediate	Initial End Effect	Damers	s		
5.4.2.6		Incorrect Insertion Direction Controller Position received inappropriately as BACKWARD instead of 'FORWARD	-TIU Failure - ETCS onboard failure other than TIU	SH, UN, PT RV	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'BACKWARD' while the actual is 'FORWARD')	roll away protection function will inhibit the forward movement instead of the backward movement	Rolling in a backward slope is possible.	Driver knows which direction is selected.	Catastrophic	TI-5	
5.4.2.7		Incorrect Insertion Direction Controller Position received inappropriately as BACKWARD instead of 'FORWARD	-TIU Failure - ETCS onboard failure other than TIU	FS, LS, SR, OS	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'BACKWARD while the actual is 'FORWARD')	roll away protection function will inhibit the forward movement instead of the backward movement	The vehicle cannot move (forward movement is inhibited by RAP while backward movement is inhibited by RMP).	Driver knows which direction is selected.	RAM Issue		Reverse Movement Protection



tef ID	Macro Functio n Data	Failure Mode	Failure Cause	Operatio nal Mode		Failure Effects		ETCS External Protection/ Mitigation/ Barriers	everity	EVEN T ID	Internal barriers
œ	nem				Local	Intermediate	Initial End Effect	Darriers	Se		
5.4.2.8		Incorrect Insertion Direction Controller Position received inappropriately as FORWARD or 'BACKWARD' instead of 'NEUTRAL'	- TIU Failure - ETCS onboard failure other than TIU	NL	Incorrect Direction Controller information sent to ETCS OBU (Direction Controller position is assumed to be 'BACKWARD' or 'FORWARD' instead of 'NEUTRAL')	Slave engine cannot proceed because it is coupled to a leading engine.	-	-	RAM issue		Leading vehicle controls the slave vehicle (S-026 §4.4.15.1.1.1)



#### 5.4.3 Train Integrity

The interface is not standardized in [Ref. 2].

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#### 5.4.4 Traction Status

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	Failure Effects			ETCS External Protection/ Mitigation/ Barriers	everity	Event- ID	Internal barriers
œ					Local	Intermediate	Initial End Effect	Barriers	Š		
F.		Traction Status (ON/OFF)	Level NTC only								
5.4.4											



#### 5.4.5 Set Speed

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects	i	ETCS External Protection/ Mitigation/ Barriers	everity	Event- ID	Internal barriers
					Local	Intermediate	Initial End Effect	24.11010	Ň		
5.4.5.1	Set Speed	Delay Deletion Corruption Insertion Wrong input Set Speed (state and/or speed value)	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, PS	False Set Speed Information transmitted to ETCS OBU	ETCS DMI shows wrong 'Set Speed' information	No effect.	Driver knows the cruise speed he has already set at vehicle's traction control.	RAM Issue		



#### 5.5 Train Data

#### 5.5.1 Type of train data entry

tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/ Barriers	everity	Event- ID	Internal barriers
Ľ.					Local	Intermediate	Initial End Effect	Durnoro	Š		
5.5.1.1	Train data - Type of train data entry	Absent Incorrect Failure or delay to report Type of train data entry	- TIU Failure - ETCS onboard failure other than TIU	SB	Type of Train Data Entry change not sent or delayed on- board	At train data entry procedure ETCS DMI shows the incorrect Train Data window (see 11.3.9.6 [Ref. 3]).	No Effect	Driver shall be informed on the type of train when Train Data entry is selected.	RAM Issue		



#### 5.5.2 Train data Information

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effec	cts	ETCS External Protection/ Mitigation/ Barriors	verity	Even t-ID	Internal barriers
8					Local	Intermediate	Initial End Effect	Dairiers	Se		
5.5.2.1	Train data – Train category (Cant Deficiency)	Delay Deletion Corruption Insertion Incorrect Reception of Cant Deficiency information (lower than real)	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	False Cant Deficiency Information transmitted to on board	Lower than real Cant Deficiency is assumed by ETCS OBU for evaluation of SSPs. This can result in more restrictive SSPs calculation (see S-026 3.11.3.2.3).	No effect.		RAM Issue		According to the specific project implementation: On- Board Informs Driver that change in Train Data needs to be validated by Driver (3.18.3.3 and 5.17.2.2 [Ref. 1])



D	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effeo	cts	ETCS External Protection/ Mitigation/	erity	Even t-ID	Internal barriers
Rei					Local	Intermediate	Initial End Effect	Barriers	Seve		
5.5.2		Corruption Insertion Incorrect Reception of Cant Deficiency information (higher than real)	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	False Cant Deficiency Information transmitted to on board	Higher than real Cant Deficiency is assumed on ETCS OBU.Error in on-board evaluation of SSPs	Vehicle may exceed maximum authorized speed for its train category so that: - Increasing in lateral forces may result in usafe wheel force condition and increase deterioration of track - Decreasing in load on inside wheel may increase risk of vehicle overrun (especially of high wind present) - Suspension operating at performance limit reduces margin of safety associated withvehicle response to track geometry variation Risk of derailment.	Driver must confirm Cant Deficiency information via DMI. Assumption: In a specific project, this failure mode can be regarded as having a 'RAM Issue' safety severity only if adequate safety margin against derailment can be demonstrated for the vehicle exceeding maximum authorized speed for its train category.	Catastrophic	TI-10	According to the specific project implementation: On- Board Informs Driver that change in Train Data needs to be validated by Driver (3.18.3.3 and 5.17.2.2 [Ref. 1]).



f ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effect	ots	ETCS External Protection/ Mitigation/	erity	Even t-ID	Internal barriers
Re					Local	Intermediate	Initial End Effect	Barriers	Sev		
5.5.2.3	Train data – Other International Train Categories	Delay Deletion Corruption Insertion Incorrect Reception of Other International Train Categories (Train Category with a SSP higher than real)	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	False Other International Train Categories Information transmitted to on board	ERTMS/ETCS on-board system considers a wrong SSP category which it must obey.	Higher than real "Other International Train Categories" is assumed by ETCS OBU for evaluation of SSPs. This can result in less restrictive SSPs calculation (see S-026 3.11.3.2.3). Exceedance of the safe speed or distance as advised to ETCS	Driver must confirm Other International Train Category information via DMI. Product specific safeguarding	Catastrophic	TI-10	According to the specific project implementation: On- Board Informs Driver that change in Train Data needs to be validated by Driver (3.18.3.3 and 5.17.2.2 [Ref. 1]).
5.5.2.4	Train data – train length	Delay Deletion Corruption Insertion Wrong input for train length	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	False Train length Information transmitted to ETCS OBU	Wrong supervision of SSPs and TSRs	Exceedance of safe speed or distance as advised to ETCS	Operational rules for driver. Driver must confirm train length information via DMI. Product specific safeguarding.	Catastrophic	TĪ-10	According to the specific project implementation: On- Board Informs Driver that change in Train Data needs to be validated by Driver (3.18.3.3 and 5.17.2.2 [Ref. 1])



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effec	ots	ETCS External Protection/ Mitigation/	rerity	Even t-ID	Internal barriers
Ŗ					Local	Intermediate	Initial End Effect	Barriers	Sev		
5.5.2.5	Train data – traction/brake parameters	Delay Deletion Corruption Insertion Wrong input for Traction/braking parameters higher	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	False traction/brake parameters transmitted to ETCS OBU	wrong braking curve calculation	Evaluation of potential effect on safe speed and distance supervised is project specific	Application Constraint: If using Train Interface as external source for traction/brake parameter input the failure of this	ion not in this Subset		
		than real						input could have catastrophic safety severity. A project specific safety analysis is required.	Hint: Evaluat		



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode	Failure Effects		ETCS External Protection/ Mitigation/	verity	Even t-ID	Internal barriers	
2					Local	Intermediate	Initial End Effect	Barners	Se		
	Train data –	Delay									
	maximum	Deletion									
	train speed	Corruption									
		Insertion									
		Assumption:									
		Maximum train									
		speed is not									
2.6		transmitted via TI.									
.5.		Under the above									
ω,		assumption failures									
		nave no salety-									
		the system If it is									
		used durina									
		operation a proiect									
		specific safety									
		analysis will be									
		needed.									



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effeo	cts	ETCS External Protection/ Mitigation/ Barriers	verity	Even t-ID	Internal barriers
Ľ.					Local	Intermediate	Initial End Effect	Damers	Se		
5.5.2.7	Train data – loading gauge	Delay Deletion Corruption Insertion Wrong input for loading gauge	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	False loading Gauge transmitted to ETCS OBU	vehicle enters a route although not suitable	collision with side barriers	Operational rules for driver Lineside indications and driver's route knowledge product specific safeguarding traffic planning	Catastrophic	TI-10	According to the specific project implementation: On- Board Informs Driver that change in Train Data needs to be validated by Driver (3.18.3.3 and 5.17.2.2 [Ref. 1])
5.5.2.8	Train data – axle load category	Delay Deletion Corruption Insertion Wrong input for axle load	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	False Axle Load Category transmitted to ETCS OBU	train enters a route although not suitable	derailment	operational rules for driver Lineside indications and driver's route knowledge product specific safeguarding	Catastrophic	TI-10	According to the specific project implementation: On- Board Informs Driver that change in Train Data needs to be validated by Driver (3.18.3.3 and 5.17.2.2 [Ref. 1])



ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effec	ots	ETCS External Protection/ Mitigation/	verity	Even t-ID	Internal barriers
8					Local	Intermediate	Initial End Effect	Barners	Se		
5.5.2.9	Train data – Train data information – Traction system(s) accepted by the engine	Delay Deletion Corruption Insertion Incorrect rinput reception of unaccepted traction system	- TIU failure - ETCS onboard failure other than TIU	All modes expect IS, SL, NL, PS, RV	Route unsuitability is not detected	Closest location corresponding to the unsuitability is not considered as EOA and SvL	The train is not tripped when overpassing the location of the route unsuitability. Damage of the engine		RAM issue		
5.5.2.10	Train Data - train fitted with airtight system	Delay Deletion Corruption Insertion Wrong input received on board so that the airtight system is assumed as available onboard when actually it is not	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	Airtight system available received from external interface when it is not available. OBU informs driver.	ETCS OBU control of Air conditioning intake has no effect.	-		No Effect		



۹D	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effeo	cts	ETCS External Protection/ Mitigation/	erity	Even t-ID	Internal barriers
Rei					Local	Intermediate	Initial End Effect	Barriers	Sev		
5.5.2.11		Delay Deletion Corruption Insertion Wrong input received on board so that the airtight system is falsely assumed as not available	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	Airtight system received falsely as not available from external interface. OBU informs driver.	Air conditioning intake is not controlled automatically.	Passenger could be affected by sudden change of pressure or noxious air coming inside train.	Opening/Closing air conditioning intake can be manually controlled onboard Product specific safeguarding	Marginal		According to the specific project implementation: On- Board Informs Driver that change in Train Data needs to be validated by Driver (3.18.3.3 and 5.17.2.2 [Ref. 1])
5.5.2.12	Train Data - List of National Systems available on- board		Level NTC only								



tef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effec	ts	ETCS External Protection/ Mitigation/ Barriers	everity	Even t-ID	Internal barriers
œ					Local	Intermediate	Initial End Effect	Damers	Š		
5.5.2.13	Train Data - Axle number	Delay Deletion Corruption Insertion Wrong input for Axle number	- TIU failure - ETCS onboard failure other than TIU	All modes except IS, SL, NL, PS, RV	Wrong number of axles is used by external equipment/ETC S	Level 2 Only: Wrong number of axles transmitted to RBC.	-	Assumption: This failure mode can be regarded as having a 'RAM Issue' safety severity only if it can be assumed that axle number information is used for operational purpose and is not safety related. If this assumption is not fulfilled, a project specific analysis is needed.	RAM Issue		



### 5.6 National System Isolation

ef ID	Macro Function Data Item	Failure Mode	Failure Cause	Operation al Mode		Failure Effects		ETCS External Protection/ Mitigation/ Barriers	verity	Event- ID	Internal barriers
8					Local	Intermediate	Initial End Effect	Dainers	Se		
		National	Level NTC								
_		System	only								
2		Isolation (NTC									
5		isolated / NTC									
		not isolated)									

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# 6. TRACEABILITY

This section lists the mandatory functions analysed and cross reference them to the SRS [Ref. 1] to the FIS TIU [Ref. 2], ERA DMI [Ref. 3] and STM FFFIS [Ref. 4].

Name	Reference in FIS TIU [Ref. 2]	Reference in SRS [Ref. 1]	Input / Output
Sleeping	2.2.1	4.4.6 / 4.6.3	Input
Passive shunting	2.2.2	4.4.20 / 4.6.3	Input
Non-Leading	2.2.3	4.4.15 / 4.6.3	Input
Isolation	2.2.4	4.4.3.1.1	Output
Service brake command	2.3.1	3.13.2.2.7 / 3.14.1	Output
Brake pressure	2.3.2	3.13.2.2.7 / A.3.10	Input
Emergency brake command	2.3.3.	3.13.10 / 3.14.1 / 4.4.4 / 4.4.5 / 4.4.13	Output
Special brake inhibition Area – Trackside Orders	2.3.4	3.12.1 / 3.13.2.2 / 5.20.5	Output
Special brake status	2.3.6	3.13	Input
Additional brake status	2.3.7	3.13	Input
Change of traction system	2.4.1	3.12.1	Output
Powerless section with pantograph to be lowered - Trackside orders	2.4.2	3.12.1	Output
Air tightness Area-Trackside orders	2.4.4	3.12.1	Output
Station platform	2.4.6	3.12.1	Output
Powerless section with main power switch to be switched off -Trackside orders	2.4.7	3.12.1	Output
Traction Cut Off	2.4.9	3.13.2.2.8	Output
Change of allowed current consumption	2.4.10	3.12.1	Output
Cab Status	2.5.1	4.6.3	Input
Direction Controller	2.5.2	3.14.2 / 5.13.1.4	Input
Train integrity	2.5.3	3.6.5.2.1	Input
Set Speed	2.5.5	4.7.2	Input
Train Data information	2.6.2	3.18.3 / 5.17	Input

#### Table 1 – SRS references

Name	ReferenceinFISTIU [Ref. 2]	Reference in DMI [Ref. 3]	Input / Output
Set Speed	2.5.5	8.2.3.9	Input
Type of train data entry	2.6.1	10.3.9.6	Input

#### Table 2 – DMI references

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Name	Reference in FIS	Reference in STM	Input / Output
	TIU [Ref. 2]	[Ref. 4]	
Service brake command	2.3.1	5.2.5	Output
Emergency brake command	2.3.3	5.2.5	Output
Special brake inhibit – STM Orders	2.3.5	5.2.4.3	Output
Pantograph-STM orders	2.4.3	5.2.4.3	Output
Air tightness-STM orders	2.45	5.2.4.3	Output
Main power switch-STM orders	2.4.8	5.2.4.3	Output
Traction Cut Off	2.4.9	5.2.4.3	Output
Cab Status	2.5.1	5.2.4.4	Input
Direction Controller	2.5.2	5.2.4.4	Input
Traction status	2.5.4	5.2.4.4	Input
National System isolation	2.7	10.3.3.5, 10.3.3.6 e), 10.14.1.2	Input

Table 3 – STM references



## 7. CONCLUSIONS

No inconsistencies and open points were found during the analysis. The following assumptions have been considered on the use of ETCS information:

#### 7.1.1 Application Constraints

- 7.1.1.1 'Service Brake Command'. If the ETCS Onboard is implemented using Service Brake to protect the train against undesirable movements, then a project specific safety analysis is needed in order to show that the failure of this signal is recognized and the EB is applied as safeguarding.
- 7.1.1.2 'Brake Pressure'. If the ETCS Onboard is implemented using Service Brake to protect the train against undesirable movements and the Brake Pressure signal is used as Service Brake feedback, then a project specific safety analysis is needed in order to show that the failure of the signal has acceptable safety consequences.
- 7.1.1.3 'Special Brake Status'. If using Special Brake as available and affecting the Emergency Brake curve, the failure of the input 'Special Brake status' could have catastrophic safety severity, then a project specific safety analysis is needed in order to show that the failure of the signal has acceptable safety consequences.
- 7.1.1.4 The failure mode to this output can be regarded as having a 'RAM Issue' safety severity only if the ETCS/ERTMS on-board equipment is configured to T\_traction = T\_traction\_cut\_off (see Subset-026, section 3.13.9.3.2.3). If this assumption is not fulfilled then failure to this output shall be held as having catastrophic safety consequences and product specific safeguarding has to be considered.
- 7.1.1.5 'Cab Status'. The failure mode of this input (see FMEA ref. Id. 5.4.1.5) can be regarded as having a 'RAM Issue' safety severity under the assumption that in case of two cabs are reported active at the same time the OBU reacts by transiting in System Failure Mode and applying EB. If this assumption is not fulfilled then a project specific analysis is necessary.
- 7.1.1.6 'Cab Status'. It assumed that the vehicle has to ensure that sleeping input is received only if another cab in the train is active (i.e. another train control system (ETCS or national) provides the supervision of the train movement) (see FMEA ref. Id. 5.4.1.4).
- 7.1.1.7 'Station Platform'. The failure of Station Platform input (see FMEA ref. Id. 5.3.6.1) can be regarded as having a 'RAM Issue' safety severity only if it can be assumed that the function related to the output of Station Platform for enabling the passenger door opening is not used for safety reasons (e.g. in cases of evacuation).
- 7.1.1.8 'Train Data Train category (Cant Deficiency)'. A specific project can regard the failure mode of this input (see FMEA ref. Id. 5.5.2.2) as having a 'RAM Issue' safety severity only if adequate safety margin against derailment can be demonstrated for the vehicle exceeding maximum authorized speed for its train category. In that case a project specific analysis and safety case is necessary.



- 7.1.1.9 'Train Data Traction/brake parameters'. If using Train Interface as external source for traction/brake parameter input the failure of this input could have catastrophic safety severity (see FMEA ref. Id. 5.5.2.5). A project specific safety analysis is required.
- 7.1.1.10 'Train Data Maximum train speed'. The analysis considers that 'Maximum train speed' is not transmitted via TI (see FMEA ref. Id. 5.5.2.6). Under this assumption failures have no safety-relevant effect in the system. If the above assumption is not valid a project specific safety analysis is needed in order to show that the failure of the signal has acceptable safety consequences.
- 7.1.1.11 'Train Data Axle Number'. The failure mode of this input (see FMEA ref. Id. 5.5.2.13) can be regarded as having a 'RAM Issue' safety severity only if it can be assumed that axle number information is not used at RBC for safety-related purpose. If this assumption is not fulfilled, a project specific safety analysis is needed.



## 8. ANNEX A – LIST OF TI-XX EVENTS IDENTIFIED

Event ID	Hazardous Event Description	
TI-1	Service brake / emergency brake not commanded when required	
TI-2 (*1)	Service brake / emergency brake release commanded when not required	
TI-3	Inappropriate sleeping request	
TI-4 (*1)	Incorrect brake status (TIU Failure)	
TI-5	Incorrect direction controller position report (TIU Failure)	
TI-6a(*1)	Intentionally deleted	
TI-6b(*1)	Wrong Cabin considered as Active	
TI-7	Inappropriate passive shunting request	
TI-8	Inappropriate non leading permitted signal received	
TI-9	Intentionally deleted	
TI-10	Falsification of train data received by External Source	
TI-11	Traction Cut-Off not commanded when required	

#### Table 4 – List of TI-XX events identified

(\*1) Note that the following events are currently unused in the FMEA reported in chapter 5:

- TI-2: Covered by TI-1.
- TI-4: This event is to be referred only to service brake. A project specific analysis is only necessary in case the brake pressure is used for safety purposes related to Service brake feedback (refer 7.1.1.2).
- TI-6b: This requires a double fault and is outside the scope of this FMEA. However, the event would need to be considered in an implementation.

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