



Towards ETCS over FRMCS in Finland -Return of experience on LTE/5G based deployment

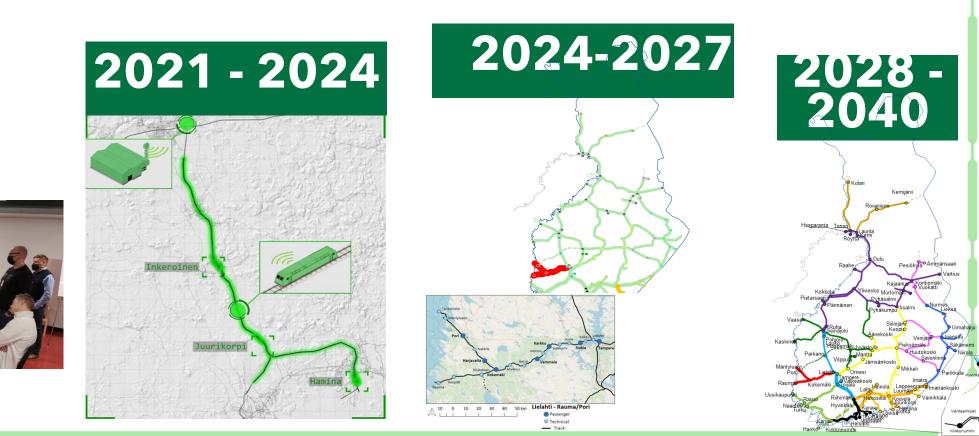
Digirail is the Finnish ERTMS program including railway digitalisation

# Digirail objectives – Radio network

- THE TARGET: In Finland FRMCS will be deployed in commercially available public radio network
  - Finland starts the process without the migration burden from GSM-R
- FRMCS is the corner stone
  - IP-based 5G network
  - · Readiness for other "Game changers"
  - Enabler of digitalisation
- The outmost target is contribute to interoperable European ETCS and FRMCS
  - Public radio network's reliability and availability are at suitable level for railway use
  - Real ETCS L2 system train controlling can be managed through public radio network



### Roadmap towards radio based system





2022

• 1st iteration was launched at the beginning of 2022.

#### TestTrack – Real system

- Length: 54 km
- Stations: 3
- ETCS-level: ETCS L2
- Radio Network (testing purposes):LTE based

#### 1st track section

- Lielahti-Rauma/Pori
- Approx.190 kilometers of single track line
- 18 stations
- Radio Network. According CCS-TSI / "pre-FRMCS" 4G/5G

#### Roll Out

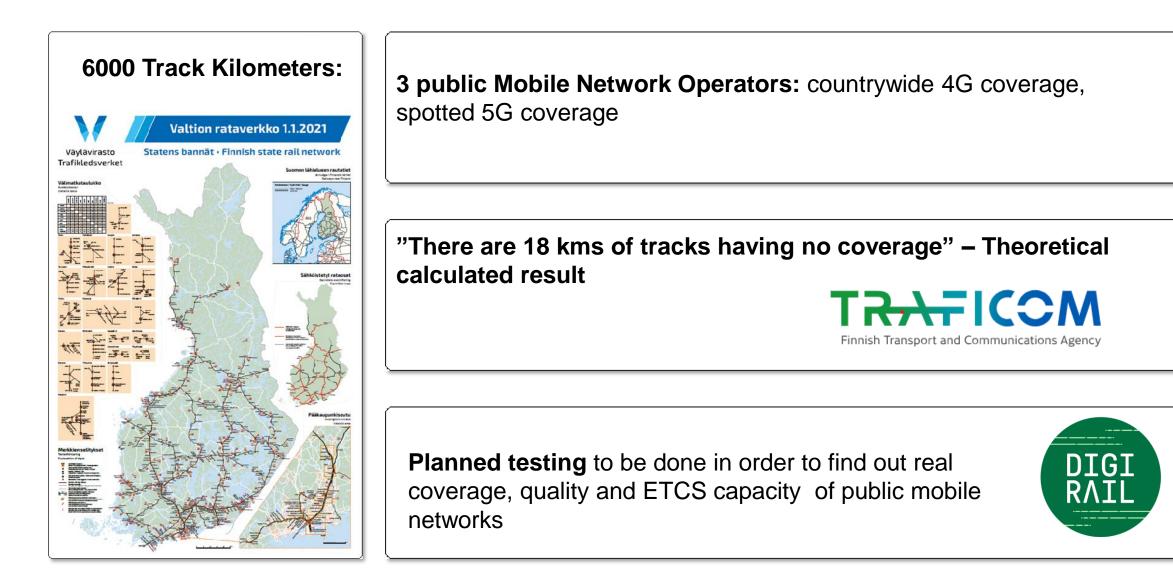
 FRMCS roll out before track infrastructue will be deployed

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 Rolling stock upgrades accordingly

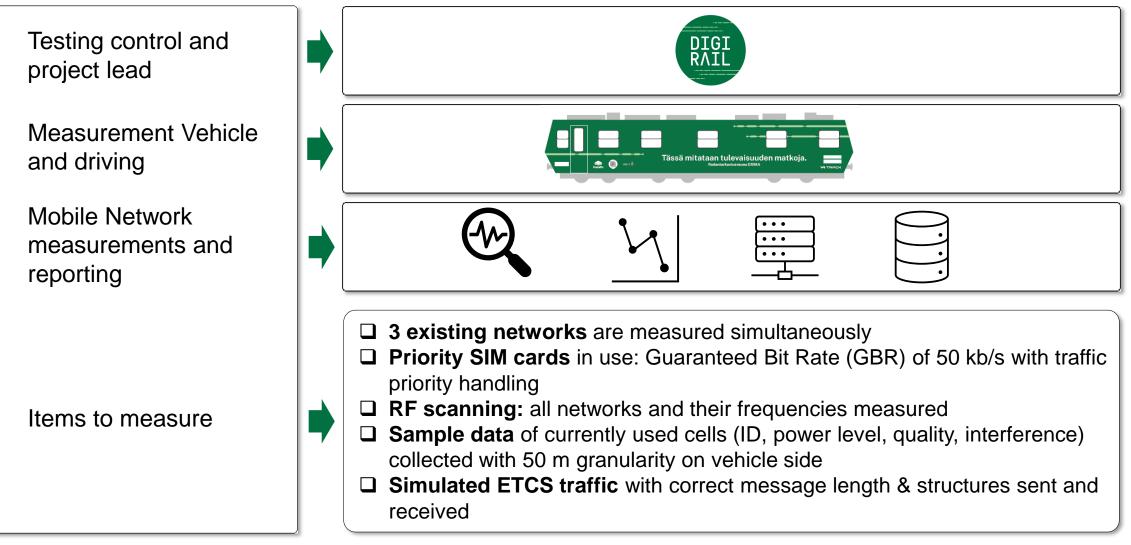


# **Starting Situation 2021**



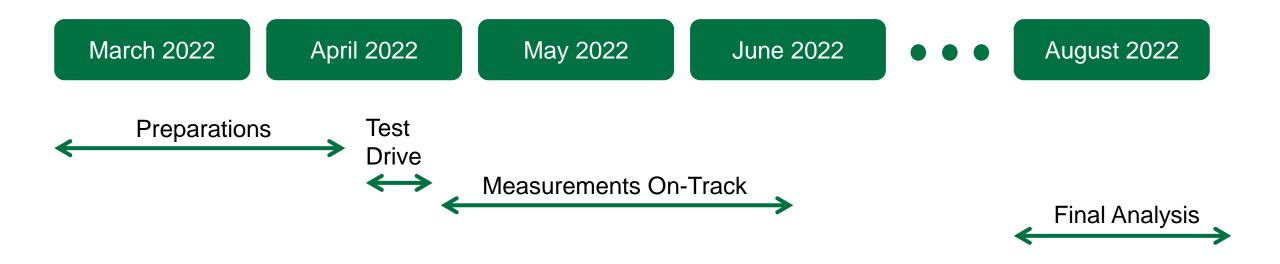
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# **Measurement division**



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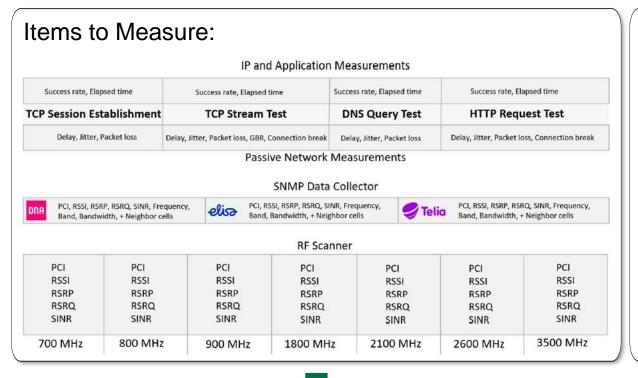
# **Measurement Project Timeline**

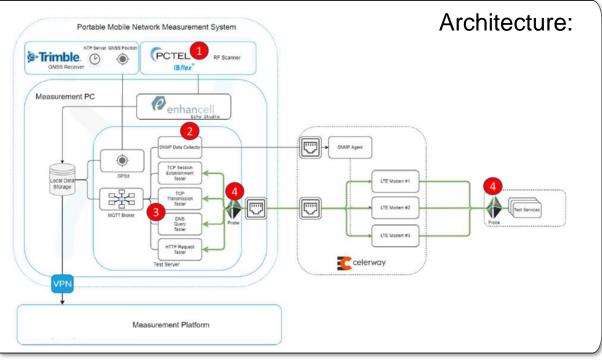


- Preparations and Test Drive are expected to be completed before Easter 2022
- Measurements On-Track will start after Easter 2022 and are expected to be completed during June 2022
- Final analysis of the measurement results is expected to be complete during August 2022
- During the measurements, intermediate weekly reports are produced about proceedings and findings



# **Measurement System**





Three public mobile networks are measured simultaneously and measurement data is collected by SNMP. RF scanning provides same information with all frequency areas. IP application measurements show how simulated ETCS traffic behaves with mobile transport.

- 1. RF Scanner
- 2. SNMP Data Collector
- 3. Test Tools for IP Application Traffic Generation
- 4. Probe for Passive Network Measurements

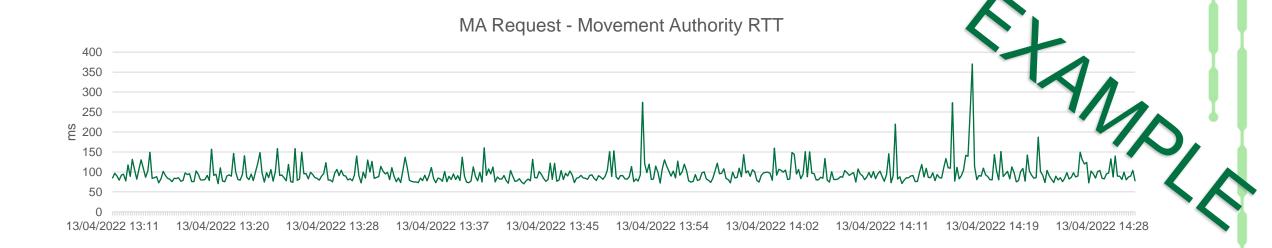
# **Preparation for testing: Test drive – Signal levels**



# **Preparation for testing: Test drive- ETCS Communication**

Simulated ETCS Traffic:

- Round-trip time is measured from Movement Authority Request to Movement Authority
- New Movement Authority Request is done in every 10s





### Another research line in Digirail Train Positioning – Vehicle Locator

- Different positioning methods are needed
  - 1. Satellite position + inertia
    - RTK-GNSS, DGNSS, EGNOS, GALILEO HAS, EGNOS HA (v 3.x)
    - Odometry
  - 2. LiDAR + sensor maps
  - 3. RADAR + sensor maps
  - 4. IMU
  - Cameras (visible and non-visible spectrum), Ground Penetrating Radar, speed radar, RfID
- Sensor fusion to improve the system
- Installation: H1/2022
- Tests: H1/2022 → H2/2022 → H1/2023

| Accuracy        | Hit rate: ~<br>50% | Hit rate: ~<br>99,7% | Integrity | Service<br>availability |
|-----------------|--------------------|----------------------|-----------|-------------------------|
| GNSS            | 1 – 1.5 m          | 4.4 m                | No        | Yes                     |
| EGNOS           | 1 m                | 2.9 m                | Yes       | Yes                     |
| DGNSS           | 0.4 – 0.6 m        | 1.2 – 1.8 m          | No        | Yes                     |
| RTK (motion)    | 0.2 m              | < 0.8 m              | Yes?      | Yes                     |
| EGNOS HA, v 3.x | 0.2 m              | < 0.8 m              | Yes       | 2027                    |
| Galileo HAS v1  | 0.2 m              | < 0.8 m              | No        | 2024                    |
| Galileo HAS v 2 | 0.2 m              | < 0.8 m              | Maybe     | ?                       |

Shedule is open for 3D localization system (incl. digital map)

- When CCS TSI is ready, 2025, 2027?
- Good map with topography and toplogy is needed to use modern 3D localization system effectively. → Current 1dimensional maps support only location from balises.
- GNSS jamming has happened in past weeks in Finland → airplanes were not able to land to some airports (use EGNOS service) → Railways can not rely only for GNSS + inertia!

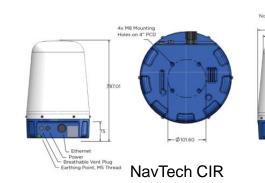
## Another research line in Digirail Test Setup at Sr2 Locomotive

#### Main components

- PC with sensor fusion software
- RTK GNSS
- Radar
- LiDAR
- IMU
- Router
- 2x pulse sensors for tacho information
- Antennas for RTK and LTE

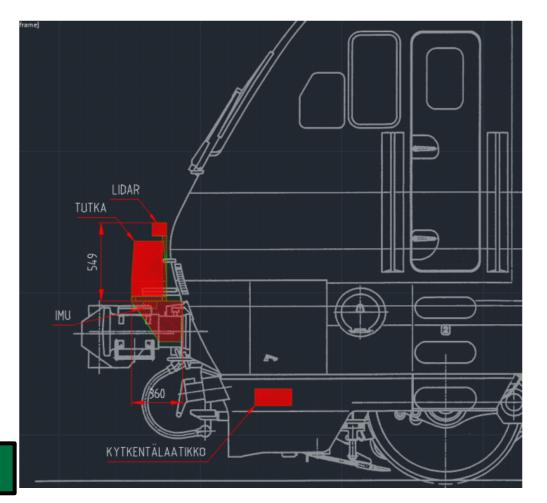


Velodyne ultra puck



206.85

Tests will start summer 2022





IMU Sensor High performance accelerometer + Super-stable gyro 「**G**T

#### FOR FINLAND'S RAILWAY NETWORK

- Maximum utilisation of investments
- Proactive maintenance, also by digital methods
- Safety in e.g. railway maintenance and level crossings
- Simplifying the infrastructure, less trackside equipment

#### Digirail 2019-2040

Foundation for the future railway traffic is formed now

### A SOLUTION THAT STANDS THE TEST OF TIME

• AI-based optimisation of traffic management

• real-time refining of data

continuously updated capacity and schedule data

dynamic reactions

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#### FOR PASSENGERS

- Punctual and safe journeys
- More connections and smooth travel chains
- Personalised passenger information

5G

#### FOR THE ENVIRONMENT

- Reduced CO2 emissions
- Shifting transport volumes to the rails from other modes of transport
- Energy efficiency through capacity optimisation and more economical and energy-saving driving

#### FOR BUSINESS

- More flexible transport services for industry
- A platform for the growth of new services
- Conditions for more sustainable business



# Thank you!



28.4.2022